

# Project 21: Wall Of Sound

## Critical Design Review

### Vectorized Acoustic Deterrence of Elephants Research

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**Sponsors:** Army Research Office: Paul Reid, Stephen Lee

**Mentors:** Dr. Pitts, Dr. Gupta, Dr. Schiefele

# Project Background



- Create a passive deterrence system which inhibits elephants from trespassing on farmland, reducing the number of casualties of humans and elephants.
- To broadcast 10Hz - 15kHz (range of elephant hearing).
- Not cause any physical or psychological harm to any organisms.
- Have to accommodate for terrain, vegetation, weather patterns, and animal interference.

# Description of Key Components

**Power Supply** - Provides power to all systems and components.

**Frequency Generator** - Creates a sinusoidal tone at 40kHz to be modulated by the sound source.

**Sound Source** - Laptop/MCU that send analog tone or sound. What the final and unmodulated sound should be at the target.

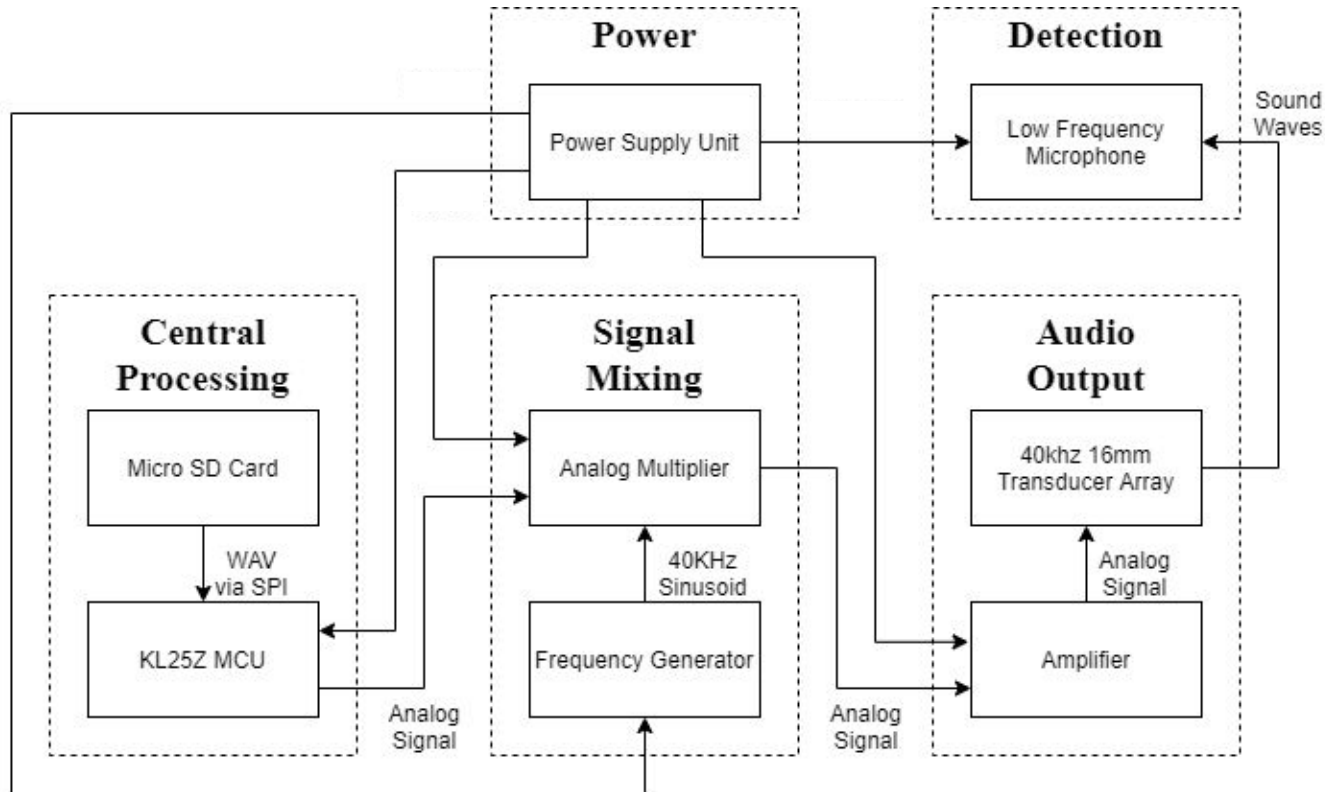
**Analog Multiplier** - Modulates sound source onto carrier via amplitude modulation.

**Amplifier** - Apply gain to modulated signal and provide power for transducer array.

**Microphone** - Verifies system functionality with frequency spectrum.

**Transducer Array** - 40kHz 16mm transducers in an array configuration to help propagate the ultrasound at longer distances.

# System Architecture Overview



# Design Changes Since PDR

## Removals

- Removed all motor instances design
- Decreased size of single hexagonal panel (331 transducers)
- Lowered priority of functioning UI
- Lowered priority of MCU & software-side of the project
- Decreased the range from 20kHz to 15kHz to target elephant specifically.

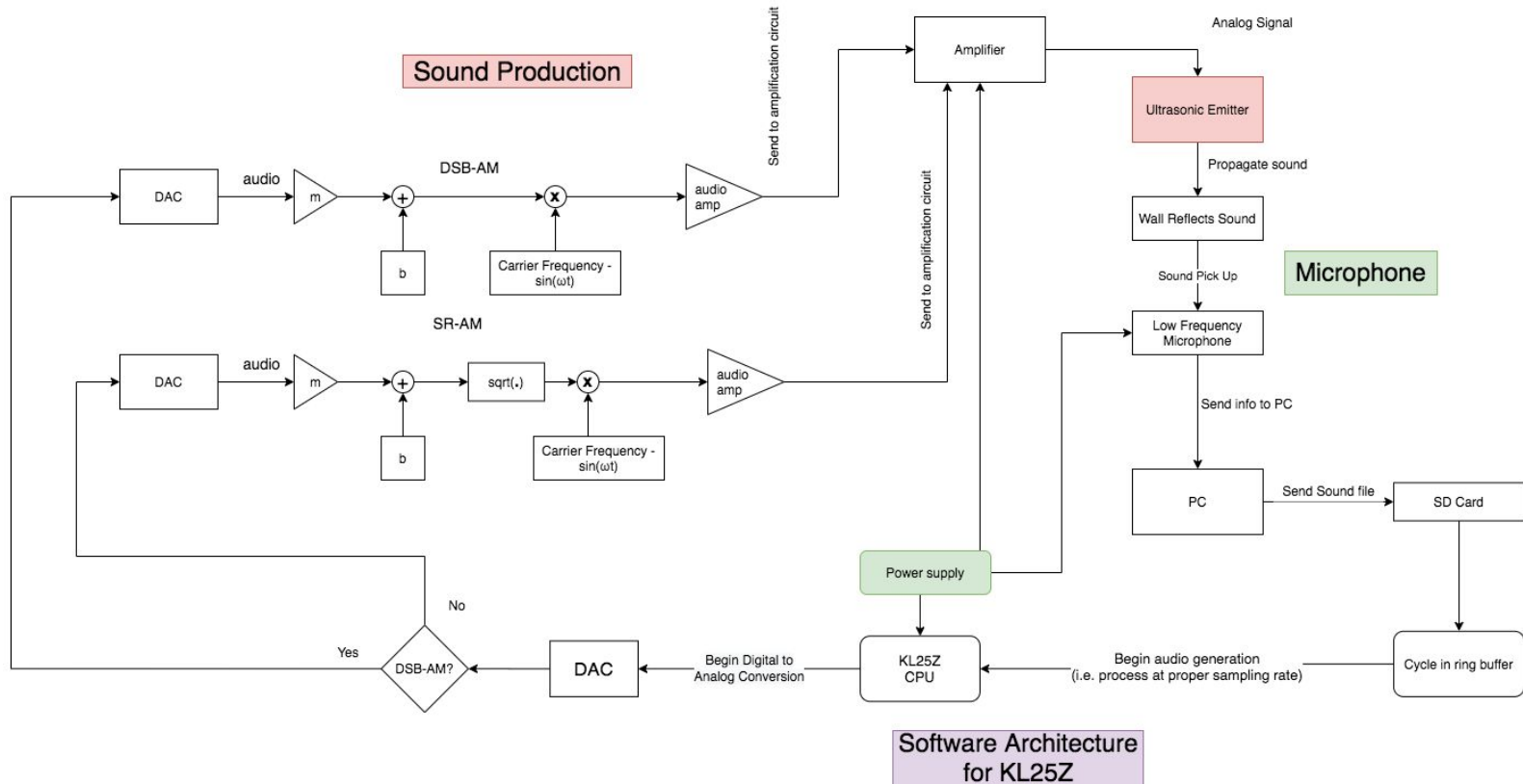
## Additions

- New modular design with smaller hexagonal panels (19 transducers)
- Multistage amplification
- Amplifier to transducer ratio (1:~20 → 1:~4-5)
- New PSU, higher wattage as well as higher voltage range

## Areas of Increased Emphasis

- Amplifier IC selection

# Final System Design



# Main Parts List

Part	Quantity
16mm 40kHz ultrasonic transducers (MSO-A1640H12T)	100
Analog multiplier (AD633)	6
Frequency generator (AD9833)	6
Extended low frequency microphone (ICS-40300)	4
Miscellaneous amplifiers (low voltage audio amplifier, operational amplifiers, etc.)	10
Miscellaneous thru-hole and SMT components	~
MCUs (KL25z, MSP4030, Arduino, etc.)	15
Plywood	5 - 6 sq. ft
2 x 4"	11 - 12 ft
8020	~

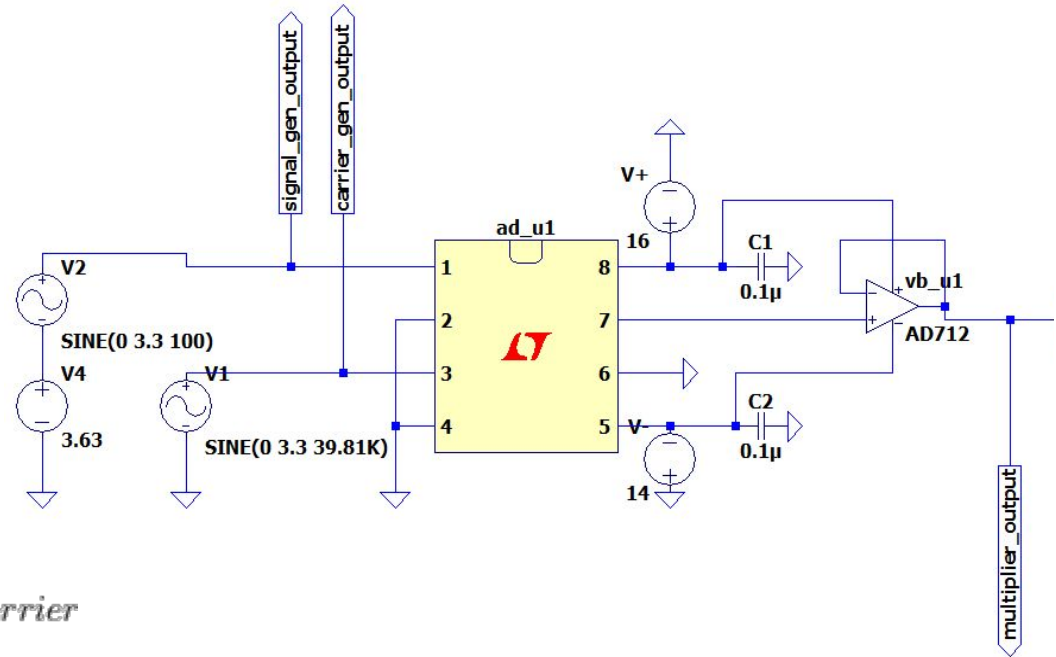
# Power Budget

Item	Current (mA)	Power (mW)	Quantity Needed	Total Power (mW)	URL
Frequency Generator	50mA	889mW	1	889mW	<a href="https://datasheets.maximintegrated.com/en/ds/MAX038.pdf">https://datasheets.maximintegrated.com/en/ds/MAX038.pdf</a>
Microcontroller (Laptop)	~	~	1	~	
Multiplier	40 mA	500 mW	1	500mW	<a href="https://www.tme.eu/Document/ce5356ac4efb480c752b9e53289e2634/AD633ARZ-Analog-Devices.pdf">https://www.tme.eu/Document/ce5356ac4efb480c752b9e53289e2634/AD633ARZ-Analog-Devices.pdf</a>
Amplifier - 1	23.695 mA	426.51mW	Many (equal to 4-5x the amount of modules we end up having)	Not sure yet	<a href="https://www.ti.com/lit/ds/symlink/lm386.pdf?ts=1613132995005&amp;ref_url=https%253A%252F%252Fwww.google.com%252F">https://www.ti.com/lit/ds/symlink/lm386.pdf?ts=1613132995005&amp;ref_url=https%253A%252F%252Fwww.google.com%252F</a>
Microphone	<220 $\mu$ A	~1mW	1	~1mW	<a href="https://invensense.tdk.com/wp-content/uploads/2019/02/DS-ICS-40300-00-v1.3.pdf?ref_disty=digikey">https://invensense.tdk.com/wp-content/uploads/2019/02/DS-ICS-40300-00-v1.3.pdf?ref_disty=digikey</a>



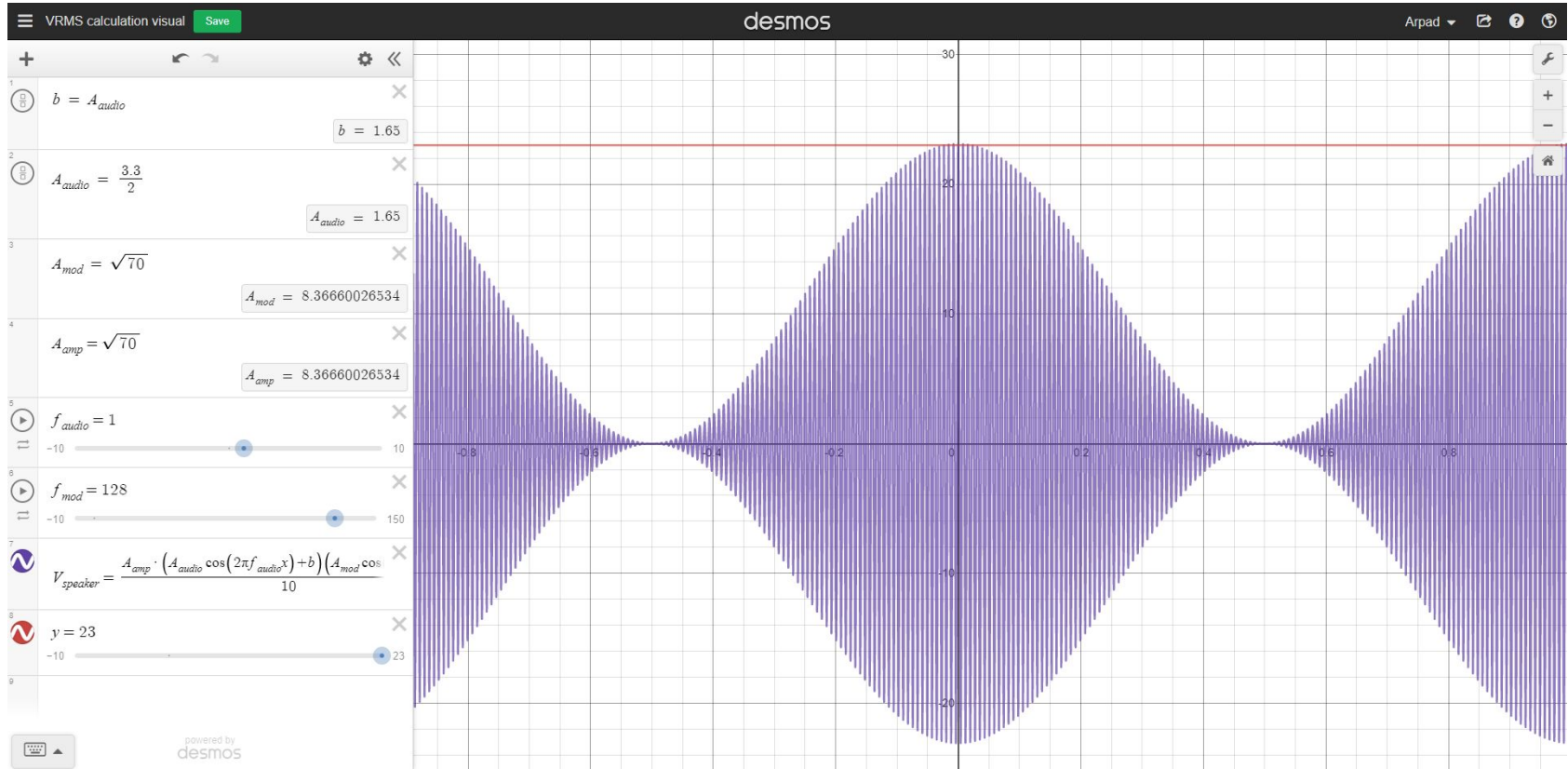
# Schematic - Multiplier (AD633)

- 40kHz sinusoidal signal from function generator
- 100Hz sinusoidal signal from signal controller
- 30V supply, oscillation absorbing capacitors
- Voltage follower to final output, ***multiplier\_output***



$$\text{MultiplierOutput} = (\text{Signal} + \text{DC}) \times \text{Carrier}$$

# 10Vrms Visual

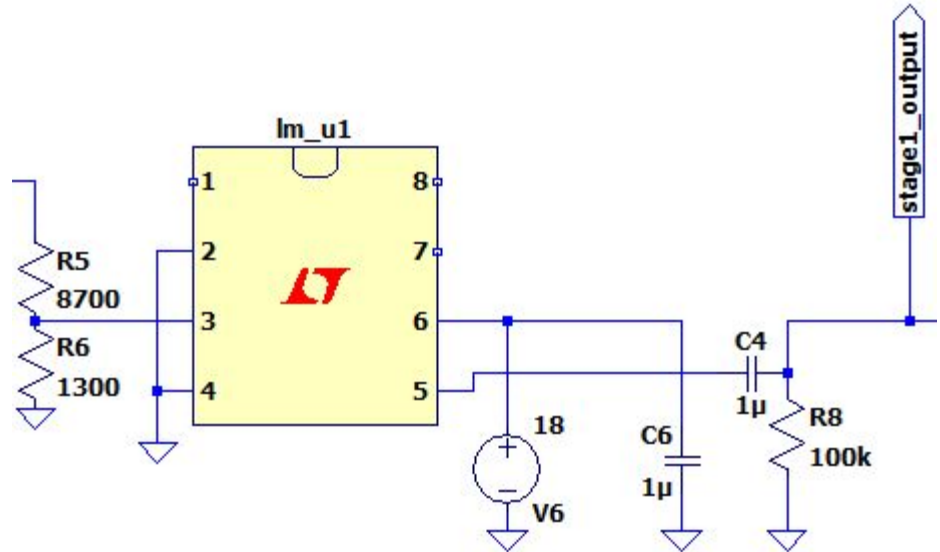


# Schematic - Amplifier

- HPF at **multiplier\_output** to remove any DC offset
- Potentiometer to adjust gain on pin 3
- Pins 1, 7, 8 are NC
- 18V supply, oscillation absorbing capacitor
- HPF at pin 5 toward **stage1\_output**

Will need second stage to get to voltage required by transducer

- Differential to negate common noise
- Frequency response

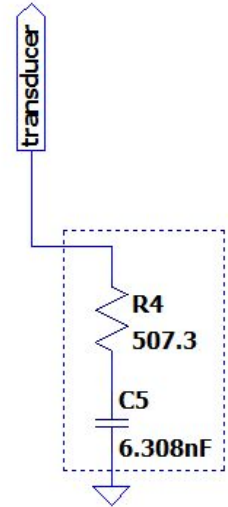


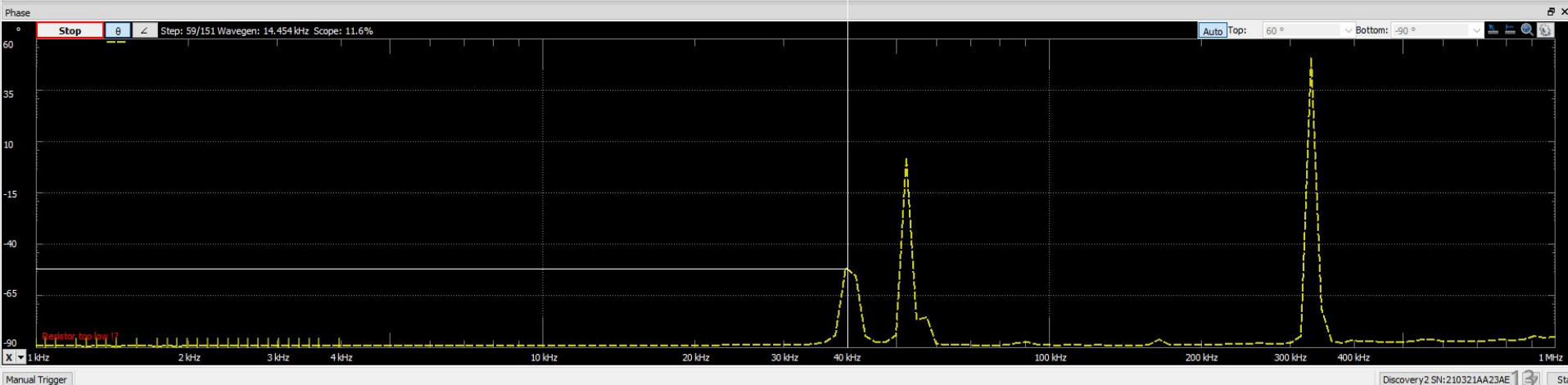
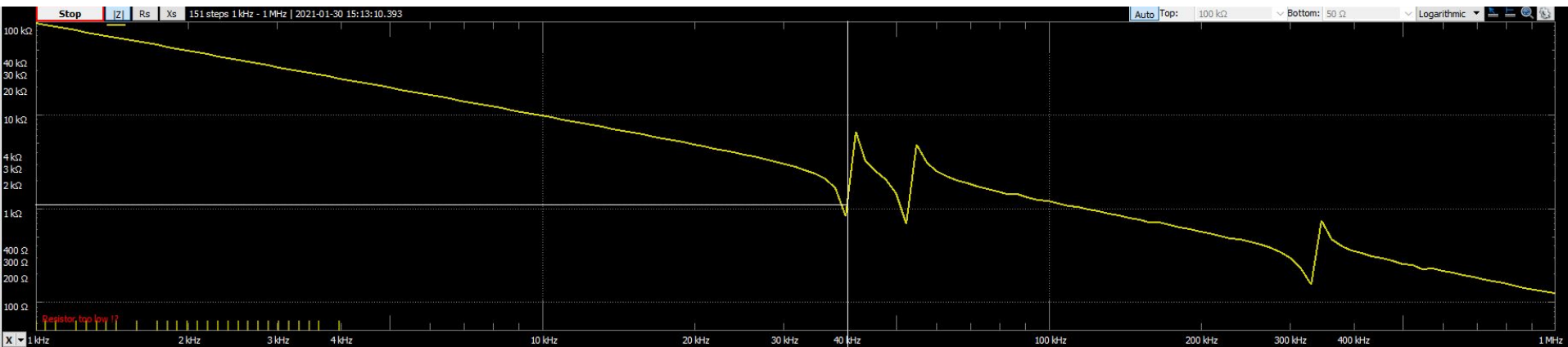
$$\text{Stage1Output} = \text{MultiplierOutput} \times 3$$

# Modeling Transducer

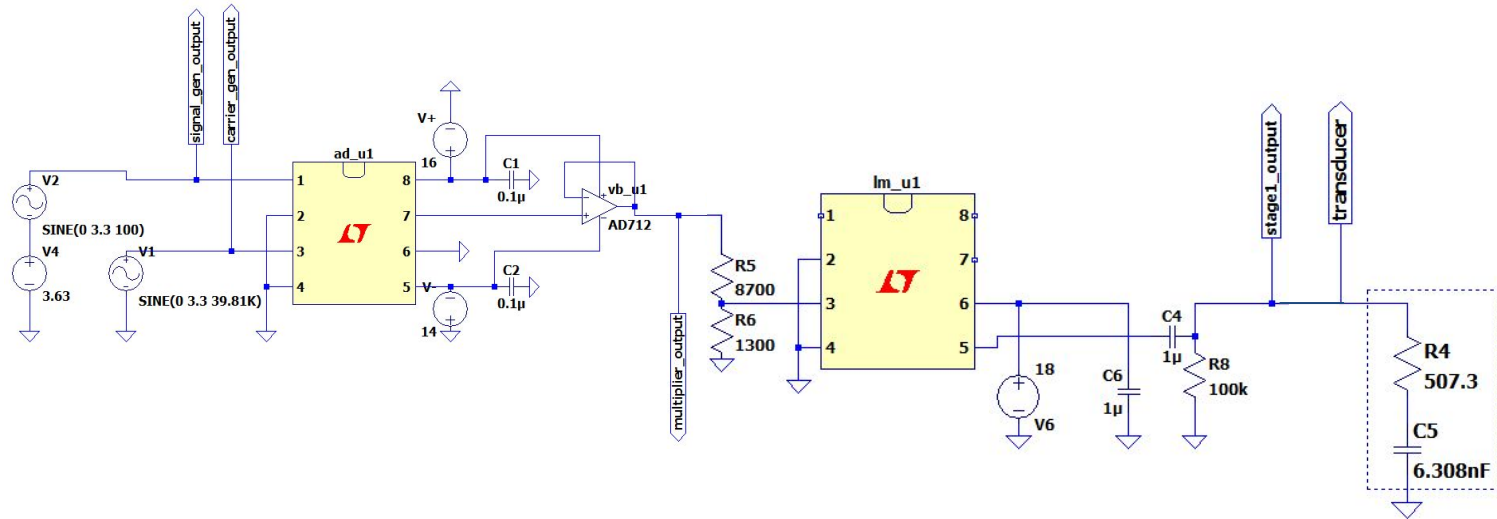
Cs: 6.308 nF	Rs: 507.3 $\Omega$	@: 39.81 kHz	$\theta$ : -51.3251 °	Q: 1.249323
Z : 811.7 $\Omega$	Xs: -633.7319 $\Omega$	$\angle$ : -50.3832 °	D: 0.8004334	

- Model of single transducer from AD2 measurements
- Software-calculated impedances, similar to LCR meter
- Have ONLY accounted for series capacitance/resistance. There are parallel ones that have measurements for, but have not modeled them (at the time of this presentation) - current task
- Transducer model on right is for 39.81kHz, hence why some of these LTspice models show that frequency rather than 40kHz

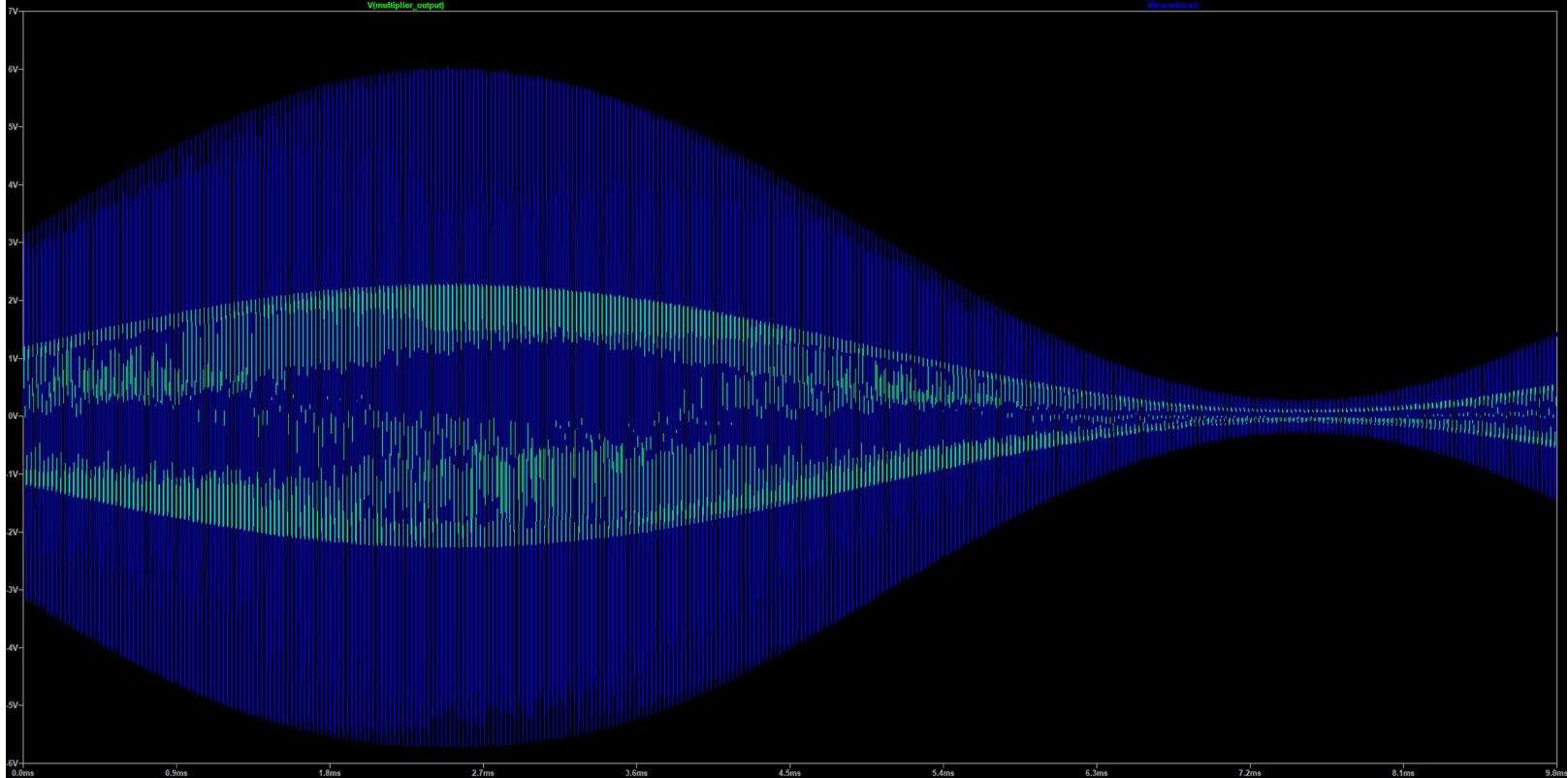




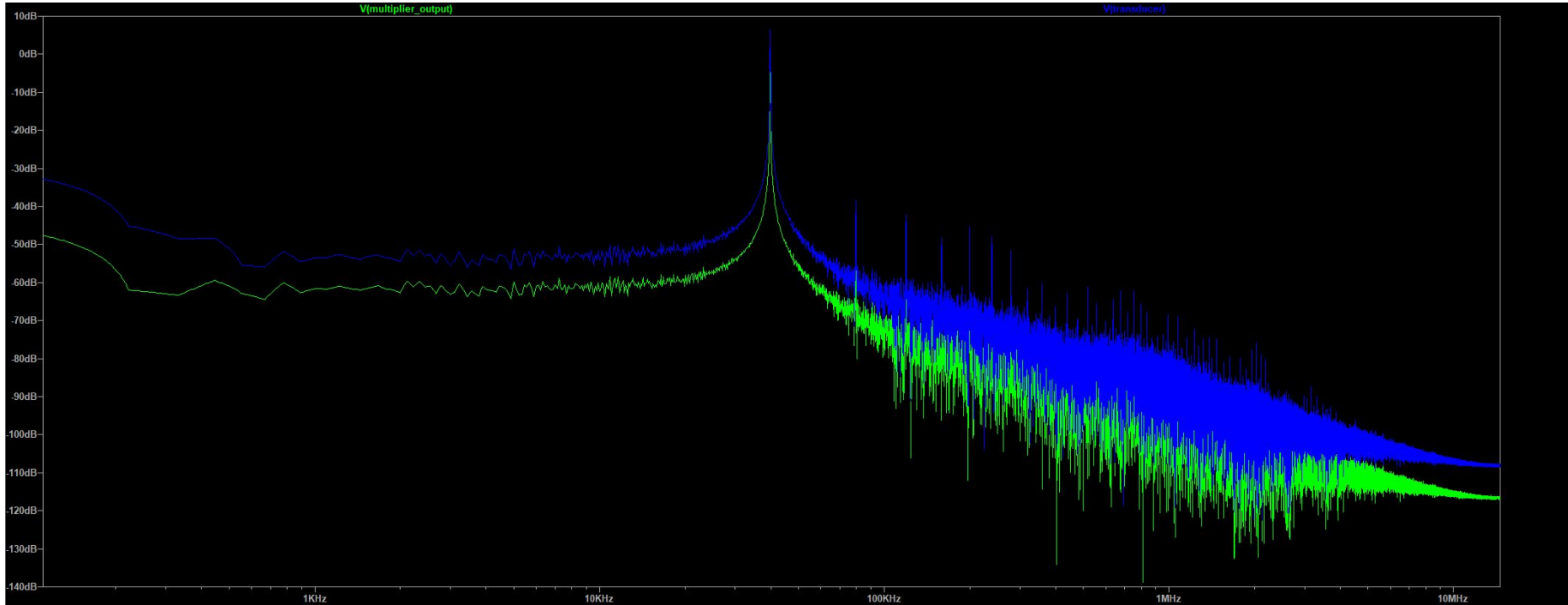
# Final Detailed Schematic Diagrams



# Simulation Results - Waveform



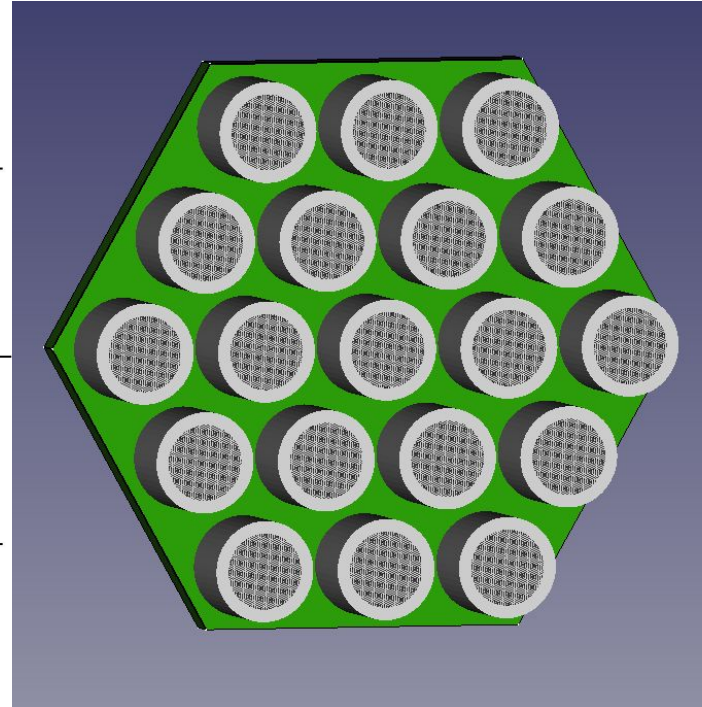
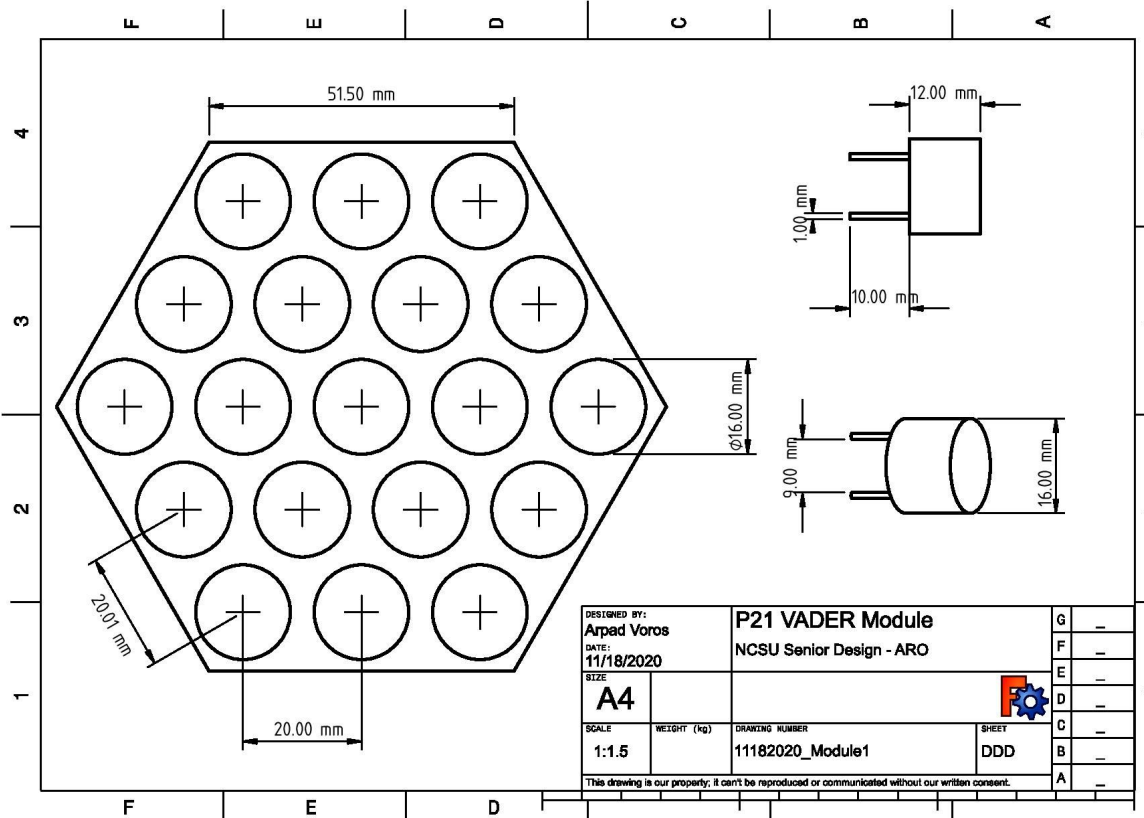
# Simulation - Spectrum



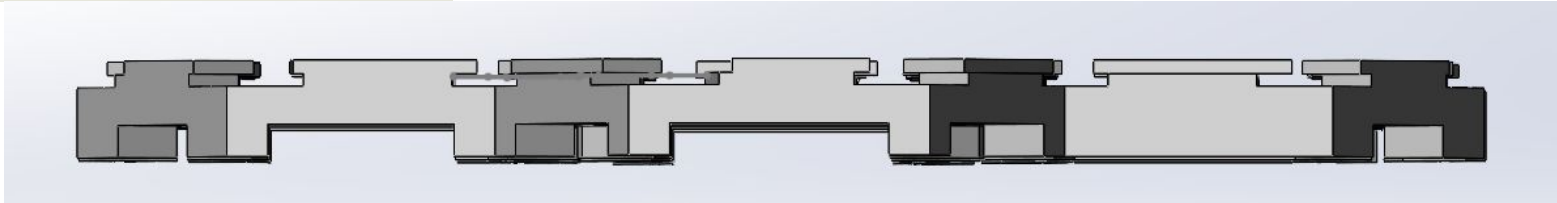
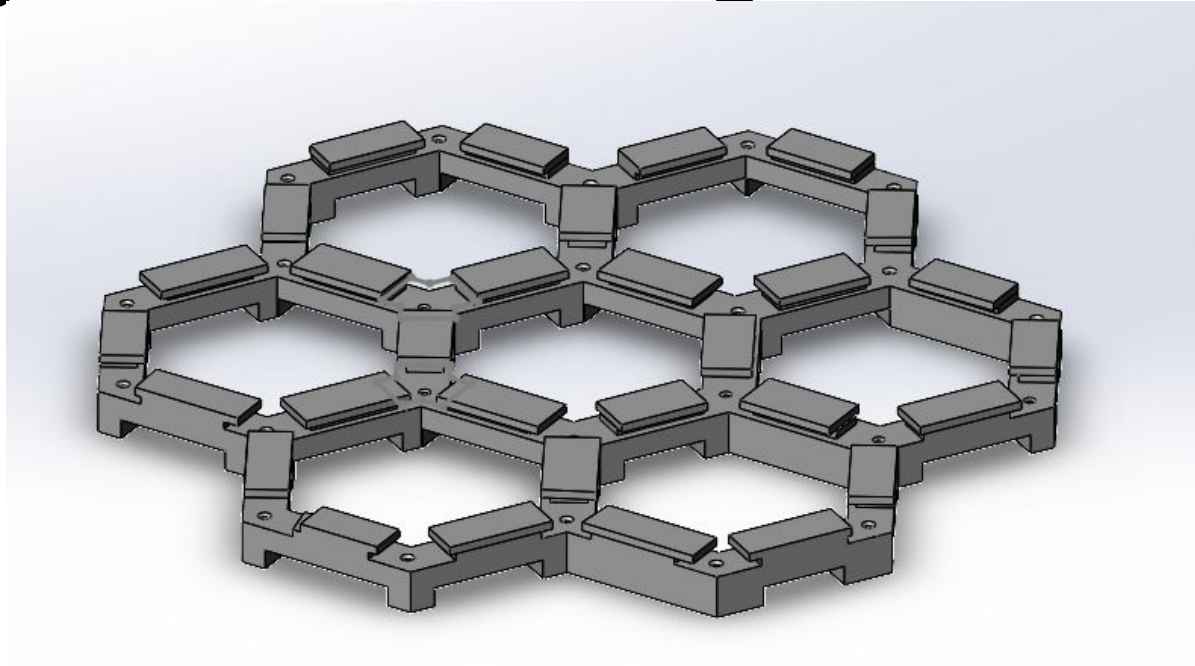
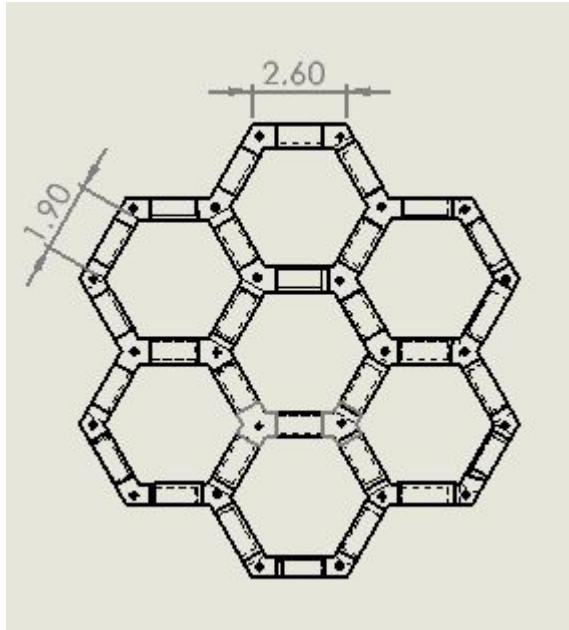
Large amount of power at 40Khz



# Hexagonal PCB Structure



# Hexagonal PCB Housing



# Final Software Overview

## Goals:

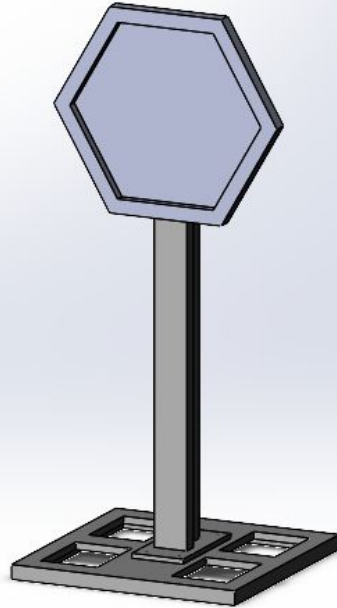
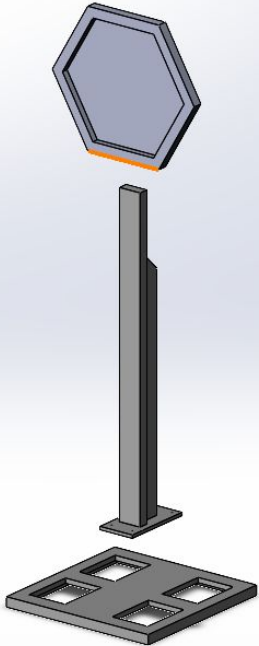
- Read sound file from SD card
- Output to DAC, 3.3V
- GUI and other processing

## **HOWEVER**

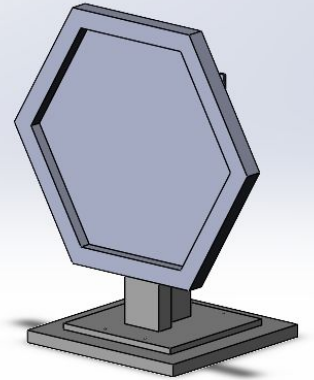
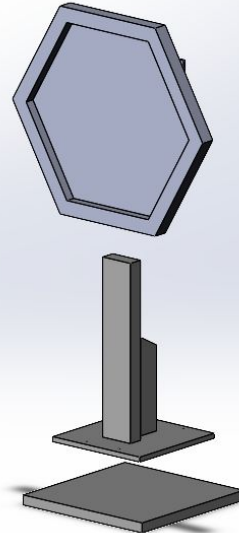
- Put on backburner for time being
- Current testbench works more effectively with a laptop
  - Quicker to change settings for tone generation
- User Interface is not as important in the proof of concept

# Final Mechanical Design

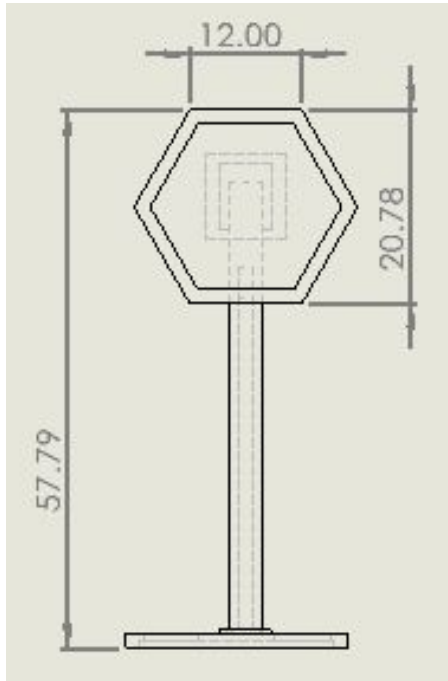
Tall Version:



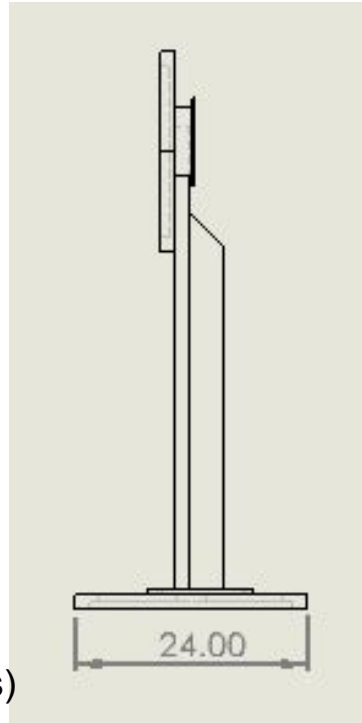
Short Version::



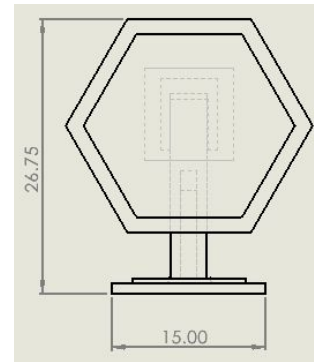
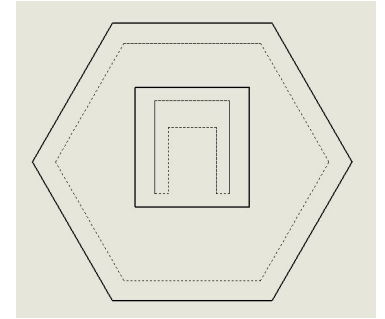
# Final Mechanical Design



Tall Version (~45 lbs with wheels)



Constant Hexagon Plate:



Short Version (~10 lbs)

# Testing And Verification for Subsystems

<b>Test Case Amplifier</b>	Determine the efficacy of the amplifier at every stage to insure no clipping or distortion with proper gain at both the 40kHz carrier and the tone signal frequency.
<b>Method</b>	Simulate in LTspice to get these desired results. Afterward connect transducers and probe at every stage. Looking at the spectrum will determine if the simulations prove to work in a desired way.
<b>Test Case Transducer Modeling</b>	Modeling the transducer in such a way that it behaves identically to the physical transducer itself in simulation and testing that to be true.
<b>Method</b>	Measuring LCR characteristics with AD2 and adapting the transducer model. Taking a known working circuit output (Sins of varying amplitude), running it through the model and in reality until we are satisfied with both behaviors being close to each other.
<b>Test Case Structural integrity</b>	Ensure that housing component is structurally sound and that base is able to support array.
<b>Method</b>	Asses base oscillations prior to array/PCB installment and make adjustments accordingly. Reassess after 3D casing is printed and PCB array is installed. Make any necessary adjustments. Analyze brittleness of 3D casing to ensure that array will not be damaged during transport.

# High-level Test and Verification

Test Case	Method
<b>Length and Intensity from source</b>	Using a microphone, measure distance away from source that sound can be identified and determine intensity at specific distances.
<b>Multidirectionality using splitting sound waves</b>	Using a microphone, ensure that the sound wave is split correctly upon contact with surface
<b>Play sound files from memory storage device</b>	Device should produce any sound file or frequency which we desire and can be tested with frequency analysis software
<b>Physical durability</b>	Basic tests for brittleness
<b>Power draw</b>	Measure current draw from subsystems and components. Change some things to accomplish a reasonable power draw.

[https://docs.google.com/spreadsheets/d/1B-i2YPVe5rdnIJBtUB8mwCOv8Y-YYvgo1uZOVVaxF\\_Y/edit?usp=sharing](https://docs.google.com/spreadsheets/d/1B-i2YPVe5rdnIJBtUB8mwCOv8Y-YYvgo1uZOVVaxF_Y/edit?usp=sharing)

# Pre Alpha Plan

	Week 1	Week 2	Week 3	Week 4	Week 5
Group	Schematic Design	PCB Action	Debug	Assembly and Debug	Alpha Demo
Nwaf	Schematic/Modeling	Microphone circuit design	Behaviour Research	Behaviour research/ Implementation	Implementation
Hunter	Determine IC for second or third stage amp	Test/debug second stage IC	Test/debug total amplification circuit	Test/debug overall schematic with all pieces	Further needed debugging for demo
Greyson	Assist with PCB development	Finalize PCB design and order from appropriate vendor	Assist with PCB debugging, reorder PCB if needed	Continue to debug PCB/working on physical housing unit	Ensure PCB is ready for demo/3D print casing
Morgan	Work on mechanical details, help find ICs and SPICE models for amplifier circuits	Test/debug circuit models for PCB, start constructing 3D printed casing	Debug PCBs, do more testing with 3D-printed casing	Continue to debug, work on mechanical assembly	Make sure everything is set up for the demo, particularly mechanical
Arpad	Model transducer - Flesh out complete circuit design, test and retest	Model transducer - Flesh out complete circuit design, test and retest	PCB layout of both circuits (multiple amp circuits per module, single mixing circuit)	PCB layout of both circuits (multiple amp circuits per module, single mixing circuit)	PCB ordered/printed, debug and move onto MCU/3D modeling of encasing



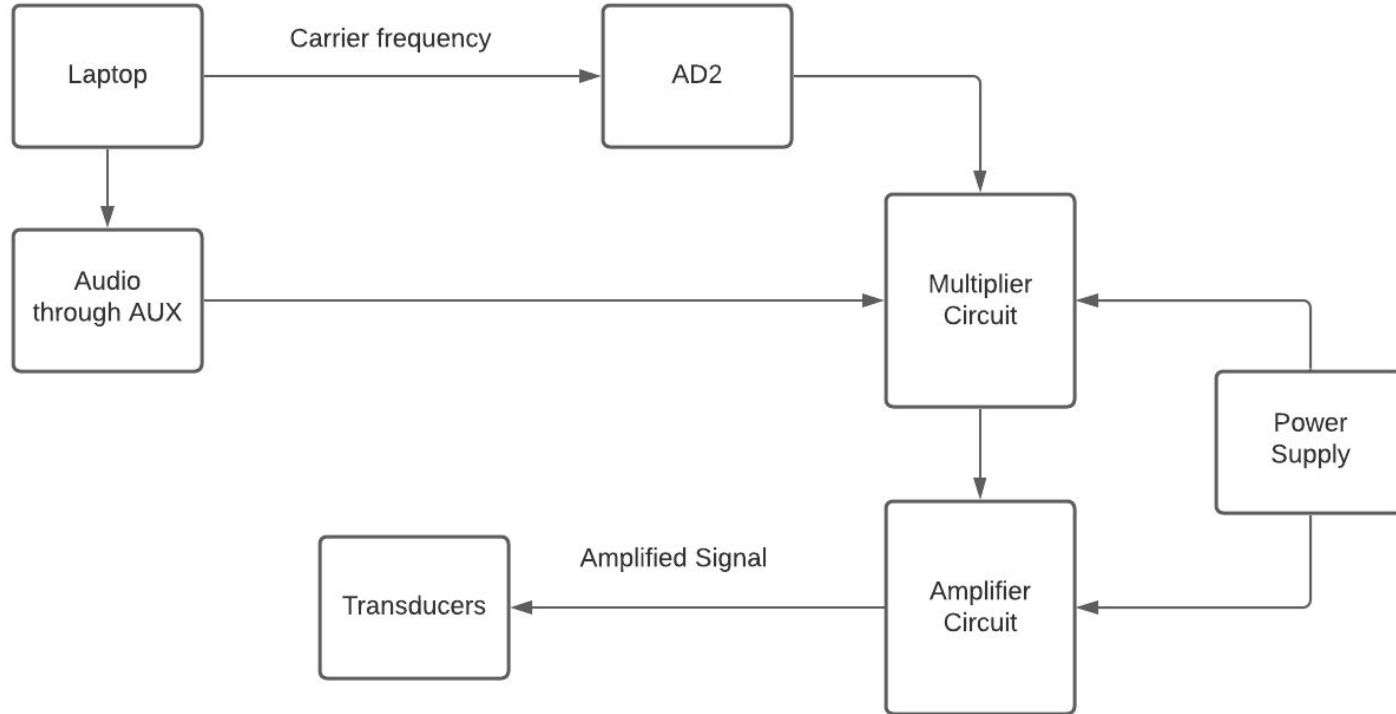
# Project Timeline

CDR February 12th	Post CDR Feb. 12 - 29	Alpha Prep Mar. 1 - 18	Alpha March 18th	Beta Prep Mar. 18 - Apr. 16	Beta April 16th		
<ul style="list-style-type: none"> <li>- Measure characteristics of transducers using LCR meter</li> <li>- Begin designing amplifying circuit with transducer as load</li> <li>- Begin PCB layout of mixing circuit</li> </ul>	<ul style="list-style-type: none"> <li>- Complete amplifying circuit, test and debug</li> <li>- Begin PCB layout of amplifying circuit</li> <li>- Complete and purchase mixing PCB</li> <li>- Begin microphone circuit (no PCB)</li> </ul>	<ul style="list-style-type: none"> <li>- Complete and purchase amplifying PCB</li> <li>- Debug and verify mixing PCB</li> <li>- Begin 3D modeling of hexagonal encasing (LCD billboard)</li> <li>- Ensure encasing includes leads which connects commons, audio source, and power</li> </ul>	<ul style="list-style-type: none"> <li>- Using PCBs, perform audio test</li> <li>- If works, use microphone to begin radiation pattern</li> <li>- If does not work, test and debug, redesign appropriate PCB(s)</li> <li>- Begin software/MCU SD card reading of audio</li> </ul>	<ul style="list-style-type: none"> <li>- Polish PCB(s) and reorder appropriately</li> <li>- Begin 3D printing hexagonal casing, fit flush with hexagonal PCB</li> <li>- Radiation pattern, if not done already</li> <li>- Complete MCU audio reading, start on a simple UI</li> </ul>	<ul style="list-style-type: none"> <li>- Present working product with at least 2 hexagonal faces linked together</li> <li>- Play various audio files from MCU</li> <li>- Simple UI for selecting audio, stopping and playing of sound</li> </ul>		
Circuit Design	PCB Layout	Purchase PCB	Debug PCB	PCB encasing	Radiation Pattern	MCU/Software	Final Prototype

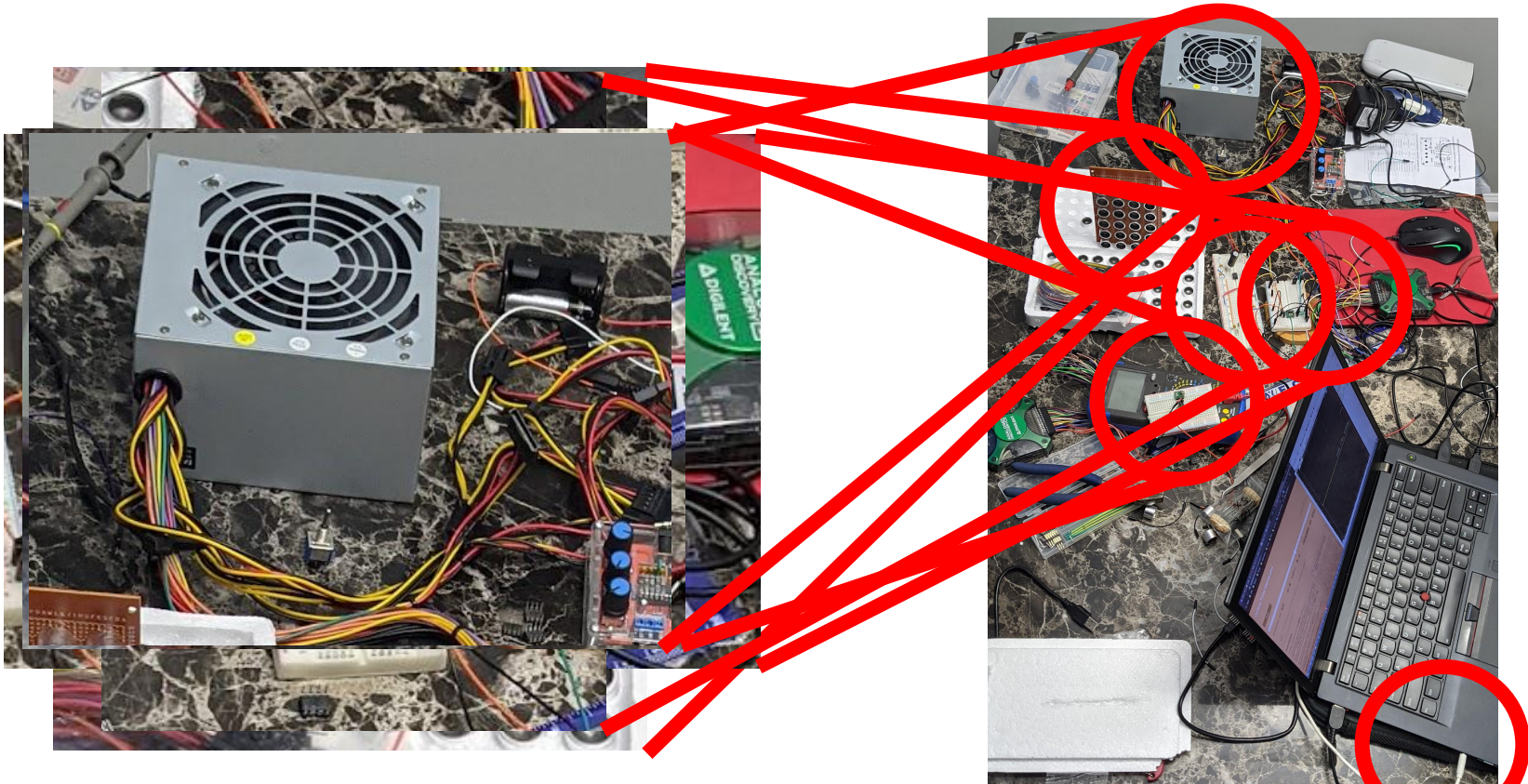
## Team VADER PCB Design Timeline



# Lab Bench Demo

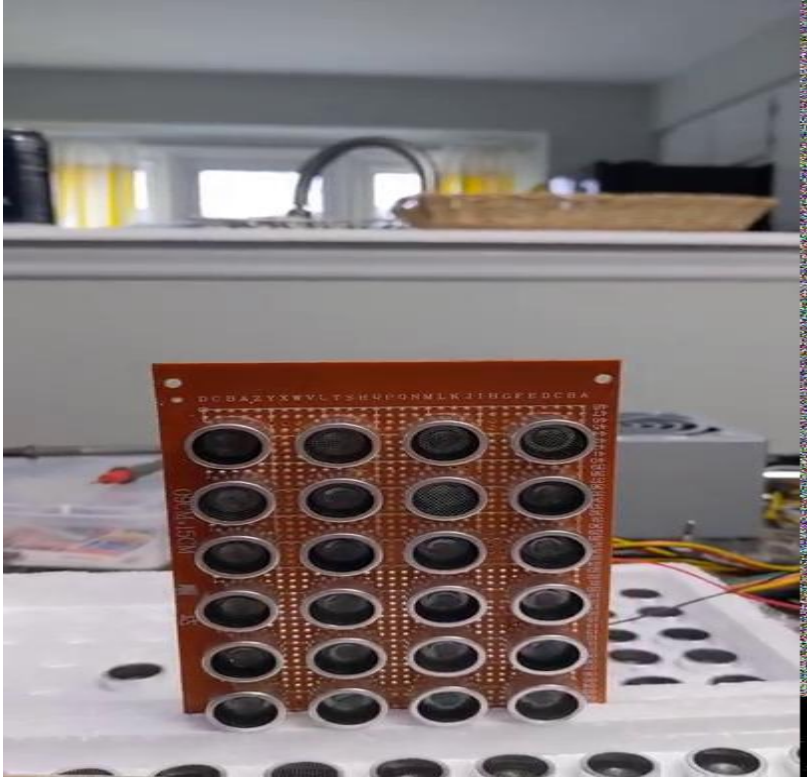


# Lab Bench Demo





# Lab Bench Demo



# Lab Bench Demo



# Project Bill of Unordered Materials

- Final Power Supply (Unknown - est.: 100 USD)
  - Renting one from Troxler for free, but will purchase a integrated PSU when the design comes to it
- Post-Stage One Amp(s) (Unknown - est.: 50 - 100 USD total)
  - RF Amps, Piezoelectric Drivers, Ultrasonic Transducer Drivers, Sonar Drivers, etc.